FY18 NDAA Section 1606 Complementary PNT Demonstration

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Stakeholder Day Postponed Joint Base Cape Cod 20 Mar 2020





Advancing transportation innovation for the public good

GPS Backup Demonstration Overview

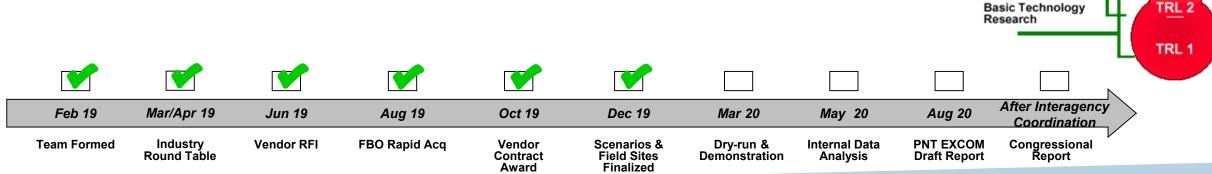
High-level Demonstration Plan Developed Under FY18 NDAA

- Joint DOT/DHS/DOD congressional briefing given Nov 2018
 - Coordination and planning efforts presented
 - DOT had yet to receive funds, transportation demonstration concept presented
 - FY20 NDAA extended period of performance to Dec 2020
- DHS Science and Technology conducted timing and positioning demonstration
 - Dec 2018 at NASA Langley/Insurance Institute for Highway Safety (IIHS) Ruckersville, VA
 - Technologies demonstrated: Locata, NextNav, Satelles (those already available at Langley)
 - Results and interim report in process
- DOT Volpe Center funded to execute demonstration Jan'19 Dec'20



NDAA GPS Backup Demonstration Status

- Demonstration Team: 20 organizations, four field sites, six host platforms
- Executing three field campaigns, [at least] three technology demonstrations,
- Awarded II high TRL vendor demonstration contracts on rapid acquisition POs
- Demonstration output products:
 - Performance report with PNT roadmap and measures of effectiveness
 - PNT strategy guide and cross-departmental coordination for PNT EXCOM





TRL 9

TRL 7

TRL 4

TRL 3

System Test, Launch

System/Subsystem

& Operations

Development

Technology Demonstration

Technology Development

Research to Prove Feasibility

Volpe Contracted PNT Vendors

















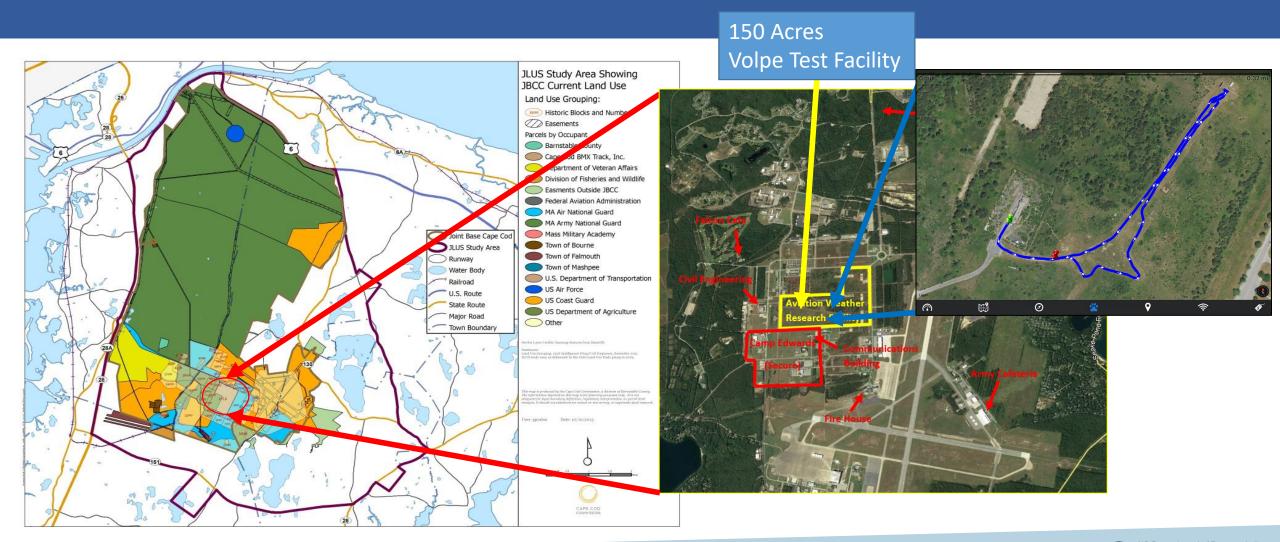








Joint Base Cape Cod (JBCC) Volpe Field Facility





Demonstration Plan (JBCC)

Joint Base Cape Cod (JBCC) Field Campaign

- 2 Weeks of Scenarios
- 5 Vendor Technologies
 - Hellen Systems
 - o PhasorLab
 - Serco & Alion
 - Satelles
 - UrsaNav

Scenario	Monday	Tuesday	Wednesday	Thursday	Friday		
72-Hour Bench Static Timing		72 Hours		As N	eeded		
eLoran Reference Station offset				All Day			
Dynamic Outdoor Positioning w/Hold		3.5 Hours (AM)			3.5 Hours (AM)		
Static Outdoor Positioning	4.5 Hours (AM-PM)				4.5 Hours (AM)		
Static Outdoor Timing	4.5 Hours (AM-PM)				4.5 Hours (AM)		
Static Indoor Positioning			1.5 Hour (PM)	1.5 Hour (PM)			
Static Indoor Timing			4.5 Hour (PM)	4.5 Hour (PM)			
Static Basement Timing			2 Hours (AM)	2 Hours (AM)			
3D Pos.		4 Hours (AM-PM)	4 Hours	4 Hours	4 Hours		
Planned Day Make-up Day							

Scenario Monday Tuesday Wednesday Thursday Friday

72-Hour Bench Static Timing 72 Hours

eLoran Reference Station offset All Day

Static Basement Timing 4 Hours (AM)



2D Platform & Reference System (JBCC)



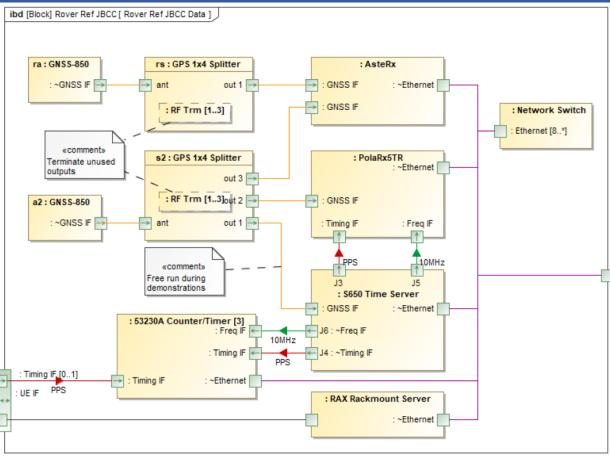


Figure 4: Rover Reference System Diagram JBCC



3D Platform & Reference System (JBCC)



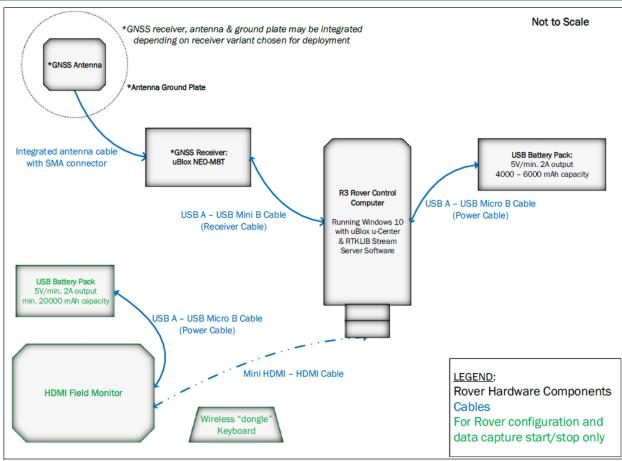


Figure 6: R3 Reference System Diagram JBCC



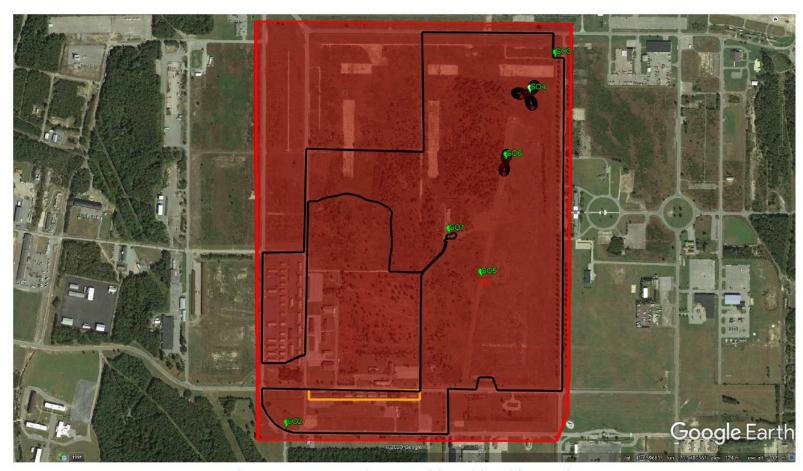
Demonstration Vendor Scope and Schedule

						Demo Platforms									
				In Situ		Terres	trial RF		Satellite	Fiber Optic	Fix	ed	Moving		
VIP Demo	day	start	end	Map Match	LF (Loran)	MF (R-mode)	VHF (passive)	WiFI (2.4 GHz)	L-Band (LEO)	PTP	Outdoor	Indoor	Static	2D (van)	3D (uas)
LaRC	13-Mar	9:00	16:00	х			Х	х	х	х	Х	Х	Х	Х	Х
JBCC	20-Mar	9:00	16:00		X	х		X	X		Х	Х	Х	X	х
			Vandars	TRX	Hellen Systems	Serco	NextNav	PhasorLab	Echo Ridge	OPNT					
			Vendors		UrsaNav			Skyhook	Satelles	Seven Solutions					

	GPS Backup Demonstration: Vendor Travel and Deliverables Schedule - Through Demonstration																					
	2019								2020													
Weeks from Award	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22
Week Start Date	4-Nov	11-Nov	18-Nov	25-Nov	2-Dec	9-Dec	16-Dec	23-Dec	30-Dec	6-Jan	13-Jan	20-Jan	27-Jan	3-Feb	10-Feb	17-Feb	24-Feb	2-Mar	9-Mar	16-Mar	23-Mar	30-Mar
Demonstration Site Visits			*																			
Site Plan				7	*																	
UE Integration Verification				,	* *																	
UE Hardware						,	* *															
Vendor Technology Setup											*	7	k									
Dry Run															*	7	*					
Demonstration																			*	7	*	
*= Travel ★ = Deliverable	Date of Award = November 4, 2019																					



Demonstration Outdoor Scenarios (2D JBCC)



- Red area fully instrumented
- Black track van routes
- Green points static points
- Orange box dismount area

Figure 9: JBCC Dynamic Van Position with Hold Scenario



Demonstration Outdoor Scenarios (3D JBCC)



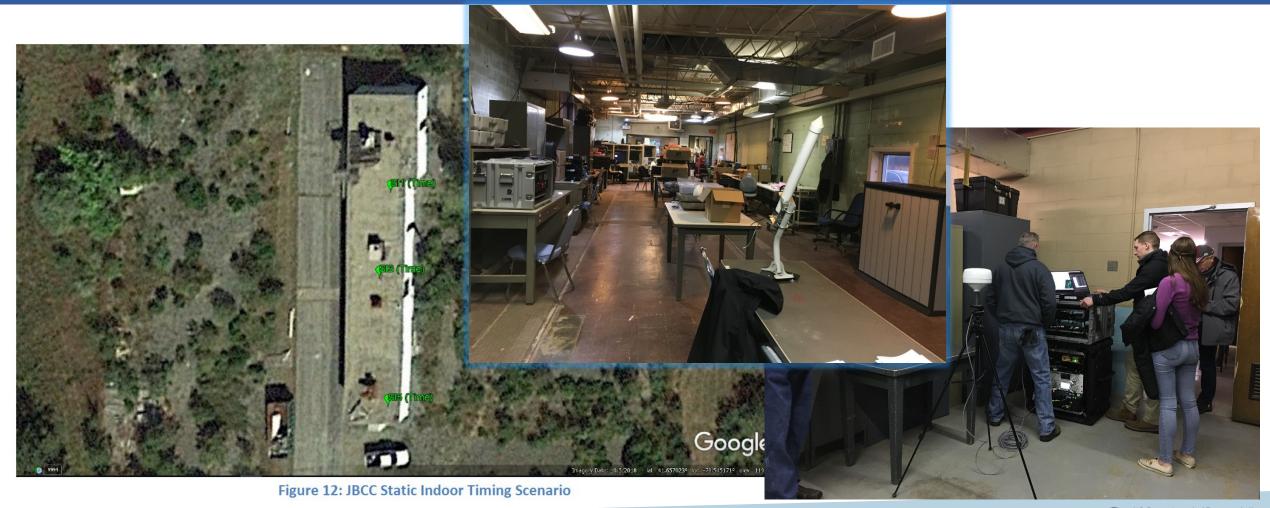
Google Earth

Figure 13: JBCC UAS Grey Route and Points

Figure 15: JBCC 3-Petal UAS Shape



Demonstration Indoor/Denied Scenarios (JBCC)



LF Reference Station Offset Scenarios (JBCC)

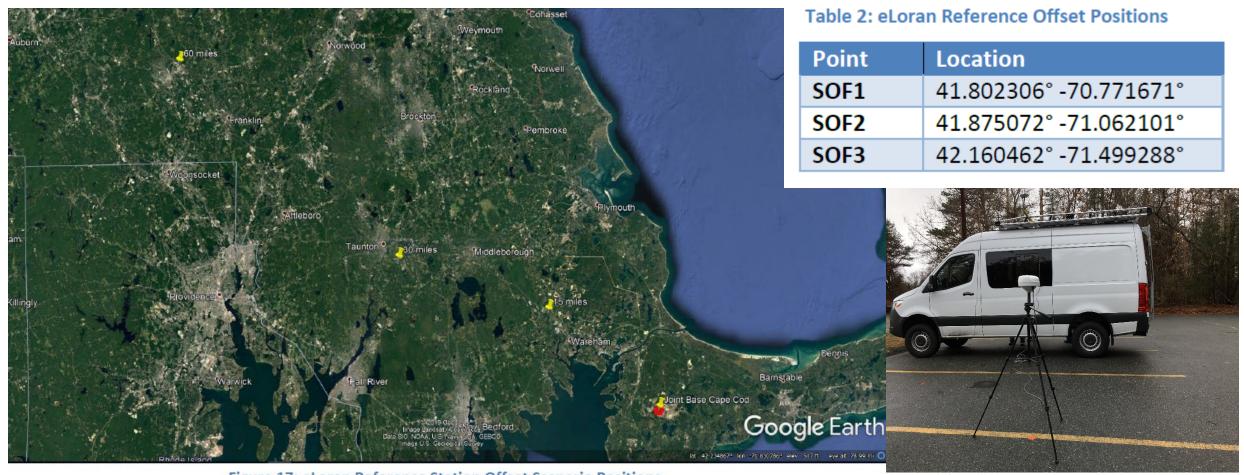


Figure 17: eLoran Reference Station Offset Scenario Positions

